

Amendments to the Specification

Kindly amend paragraph [0021] of the specification as follows:

| [0021] Referring to FIGS. 1-3, a robotic extraction cleaner 10 with dusting pad 10 is described and comprises robotic platform further comprising a top enclosure 12 and a base housing 14. The base housing 14 provides the basic structure for the robotic platform on which all other components depend for structural support. A clean solution tank 16 is removably mounted in a solution tank recess 18 formed within the top enclosure 12. A generally conical shaped recovery tank 20 is removably mounted to a flat surface formed on a top surface of top enclosure 12. A plurality of proximity sensors 24, 26 are located within corresponding sensor apertures 22 around the outer periphery of the top enclosure 12. The proximity sensors 24, 26 comprise any one or combination of commonly known sensors including infrared sensors 24, pressure sensitive sensors 26, or ultrasonic sensors affixed to the top enclosure 12 in alternating or parallel fashion. Alternating the arrangement of proximity sensors 24, 26 provides redundancy and allows for improved motion control of the robotic platform as it encounters obstacles within the room being cleaned. An electrical power switch 28 is located on a top surface of the top enclosure 12, preferably near the recovery tank 20, and controls the flow of power from one or more batteries 44 to a logic board 46, both mounted to the base housing 14 within a cavity formed by the top enclosure 12.